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# LARGE SPACE TELESCOPE ENGINEERING SCALE MODEL OPTICAL DESIGN

by

Terence A. Facey

April 1973

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Prepared Under Contract No. NAS 8-29312 THE PERKIN-ELMER CORPORATION Norwalk, Connecticut

for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION

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#### FOREWORD

This final report documents and summarizes the detailed optical design analysis of the Large Space Telescope Engineering Scale Model performed for NASA, Marshall Space Flight Center under Contract NAS 8-29312.

The study reviewed various concepts/design configurations and, with MSFC approval (reference Conceptual Design Report, Perkin-Elmer Engineering Report No. 11378), selected a single telescope/relay form for detailed design. Two fine guidance optical concepts have also been designed in detail and integrated with the telescope/relay so that MSFC can evaluate the applicability of each to the LST system. A significant part of the study was devoted to an analysis of the effects of articulation of the secondary mirror. A novel field corrector design has been developed, based upon a Perkin-Elmer adaptation of the Rosin corrector plate. This small, light-weight unit permits correction of astigmatism and field curvature in the guidance field, without need for large diameter, heavy refractive field corrector lenses.

The optical design data is presented in Section III with the overall system tolerance analysis defined in Section IV.

Unless otherwise stated, all dimensions are in millimeters and the wavelength of light is taken as 5,000Å.

#### SECTION I

#### SUMMARY

The overall objective of the Large Space Telescope (LST) Program is the near earth orbiting of a long life 3 meter diffraction-limited telescope system. This system will permit attainment of high resolution imagery, being clear of the degrading effects of the earth's atmosphere and in an environment where the low level of disturbances will allow high pointing stability. The telescope will resolve fainter objects than possible from the earth's surface and will be capable of prolonged operational periods. To attract a large user body, the system will provide a wide selection of instrument types operating over a broad spectral band and output data in a form convenient to astronomers. It will be designed for experimental versatility to allow for expected change in astronomy interest over its long lifetime and to take full advantage of the space shuttle system.

The LST Engineering Scale Model will serve as the ground-based test bench for the testing and evaluation of critical subsystems and the development of technology required for LST. The size/capability of LST will place special demands on system pointing and stabilization, optical wavefront measurement, system inflight alignment, mirror figure control and thermal control of the optical structure.

The objective of this study is to develop the detailed design and tolerance data for the LST Engineering Scale Model optical system. This will enable MSFC to move forward to the optical element procurement phase and also to evaluate tolerances, manufacturing requirements, assembly/checkout procedures, reliability, operational complexity, stability requirements of the structure and thermal system and the flexibility to change and growth.

#### 1.1 REQUIREMENTS

The baseline telescope defined for this study was a 1.2-meter, f/2. 2 primary mirror Ritchey-Chretien form with a system speed of f/12. All data optics were to be reflective. The diffraction-limited system was to produce a  $5 \, \text{min}$  data field at f/12 and a  $2 \, \text{min}$  data field at f/96 with a data field wavefront error of less than  $\lambda/10 \, \text{rms}$ . Fine image stabilization was to be achieved by articulating the secondary mirror sufficient to compensate

for  $\pm 2$  sec motion of the telescope line of sight. The design was to be modular in form with four optically independent elements: telescope, relay, fine guidance optics and coarse acquisition optics. Two telescope system designs, with differing tracking schemes, were defined by the study.

#### 1.2 TELESCOPE SYSTEM WITH IMAGE MOVER

This optical system and its principal dimensions are shown in Figure 1. The Ritchey-Chrétien (R/C) telescope objective produces a diffraction-limited 5 min diameter data field at the f/12 focal plane. The central 2 min of the field are relayed by the off-axis, reflective eight power data relay to the data sensor located in the f/96 image plane.

Diffraction-limited performance at f/96 can be achieved, of course, only if the image can be held stable to within about 0.008 sec of motion or jitter during an exposure. To achieve this performance requirement, offset tracking methods are used. Guide stars, located in the 18 min to 36 min diameter circular guidance field of the R/C are passed through pairs of Rosin plate correctors. These adjustable corrector plates will correct the off-axis astigmatism and field curvature present in the field of the R/C design. The corrected guide star image is relocated by the optical image mover to a fixed point just outside the 2 min data field. In this way the necessarily large field of view required to obtain the needed guide stars can be provided and then, without scale change, the guide star moved closer to the data star so that common, smaller, following optical elements can relay both stars. In this design the diameter of the 2 min field at f/12 is 8.37 mm and the image mover brings any guide star located within the 36 min (150 mm) diameter field into a point 6 mm off-axis at f/12, so that it is readily relayed by the following data relay system. Detailed descriptions of the Rosin corrector plates and the image mover are given in Section III of this report.

There are three basic sources of guidance error attributable to the telescope system during an exposure period:

- Movement of telescope line of sight
- Movement of data instrument due to thermal or dynamic load on support structure
- Movement of the eight power relay or any of its elements

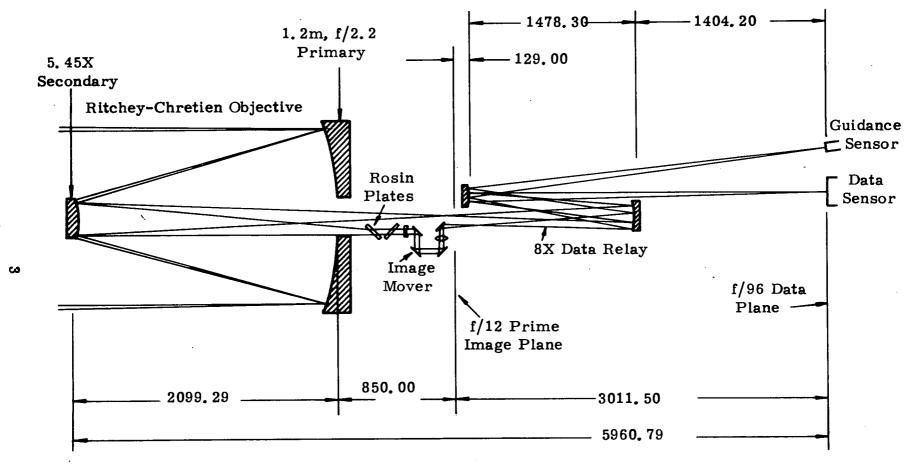


Figure 1. Ritchey-Chretien General Arrangement

The key element of the image mover design is that it provides common optical paths for both the data star and guide star. The guidance sensor, located in close proximity to the data sensor at f/96 can thus sense any of the above motions and provide the correction signal to the articulated secondary mirror. Table 1 gives the key tolerance requirements for the telescope/guidance system design. The structural stability requirements are inherently less demanding, being determined by criteria of optical focus and alignment and not by the stringent requirements of allowed jitter (0.008 sec) than would result if data sensor and guidance sensor were significantly separated and the intervening structure required to hold a true dimension.

The image mover/Rosin plate combination will require a drive to position it in the field at the selected guide star. Any drive presents operational and reliability problems but all concepts so far suggested for LST have in one form or another, to provide a drive to meet this condition. Tolerances on the absolute position of the image mover are dependent upon the accuracy to which coordinates of guide star and telescope true line of sight are known. Knowing these coordinates, the image mover must be positioned so that the guide star falls within its 30 sec field.

Because the optical relay will be relaying both data star and guidance star (and they may often differ considerably in magnitude) it will be important in this design that the optical surfaces in the relay system be extremely low in scatter characteristics.

TABLE 1. ALIGNMENT STABILITY TOLERANCE DATA TELESCOPE SYSTEM WITH IMAGE MOVER

Ritchey-Chrétien secondary decentration	±0.5 mm
Relay module decentration	$\pm 12\mu$
Relay module tilt	1.5 sec
Relay primary mirror decentration	10μ
Relay primary mirror tilt	1-0 sec
Image mover position	±0.5μ
Rosin plate angles	±0.02°
Structure (image plane) motion	±0.1 mm

# 1.3 TELESCOPE SYSTEM WITH F/12 GUIDANCE

This optical system is shown in Figure 2. The Ritchey-Chrétien telescope system and eight power data relay are identical to the system just described: they provide a diffraction-limited 5 min data field at f/12 and a 2 min data field at f/96. This design must also provide stability of ±0.008 sec at f/96. As in the initial design just described offset tracking methods are used on the guide stars in the 18 min to 36 min diameter annular guidance field. The off-axis guide star is first passed through pairs of Rosin plate correctors which correct off-axis astigmatism and field curvature. This provides a well corrected f/12 guide star image in a flat plane at f/12. The image size at f/12 is only 14 microns in diameter. A small 8X relay is used to enlarge the image prior to its passing into the guidance sensor mounted at f/12.

If no further image motion detection/stabilization is used, two sources of image error at f/96 remain:

- Movement of the instrument support structure between f/12 and f/96 due to thermal or dynamic effects
- Movement of any part of the relay system or its support structure

Table 2 gives the summary optical tolerances for the system and it is apparent that this design approach shifts the burden for good image stabilization into the structural and thermal system design areas. The difficulty of meeting the structural/thermal tolerance requirements will also most certainly increase with size of telescope system and with the internal complexity in number of data instruments, complexity of optical relay systems, quantity of subsystem equipment present and its thermal effects and maintenance/servicing requirements.

An alternate to this system is shown in Figure 3. A small light emitting diode is located in the f/12 image plane close to the edge of the data field of the R/C telescope. In this location (similar to the exit point of the image mover design) the LED can provide an optical link to a guidance sensor located in a fixed position in the f/96 image plane near the data sensor. This 'metering' link then will measure only motions of the instrument support structure and its error signal will provide a correction signal to the prime guidance sensor at f/12. In this way the secondary mirror is the single key image stabilization element and image stabilization is achieved directly to each instrument. The tolerance summary is shown in Table 3.

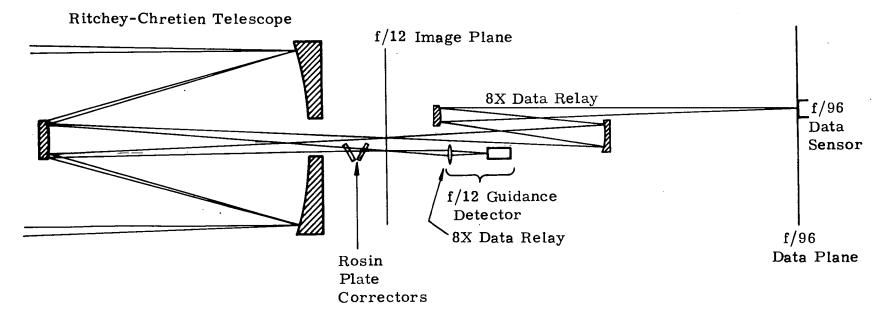


Figure 2. Ritchey-Chretien Telescope with f/12 Guidance Detector

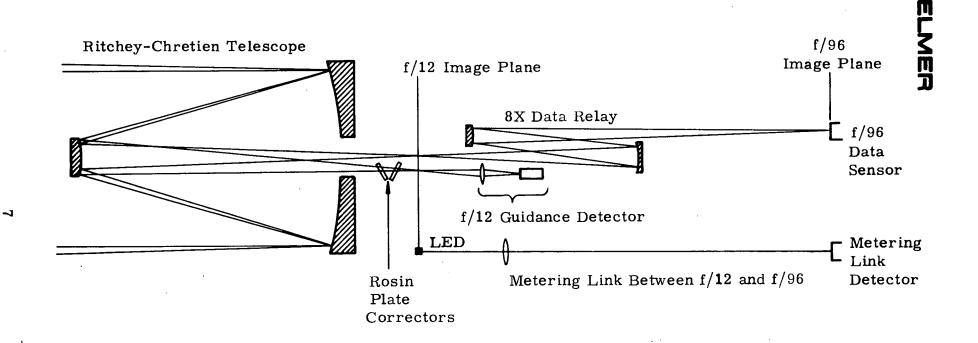


Figure 3. Ritchey-Chretien Telescope with f/12 - f/96 Metering Link

A consideration of this tolerance data shows the system to be highly improbable. Although the metering link will monitor structural flexures between the f/12 and f/96 image planes, it does nothing to alleviate the problems of stability of the relay optical elements.

The only way to monitor optical component stability, as well as overall structural stability, is to meter the system from f/12 to f/96 through the relay lens - just as the data star image does. A separate metering system involving a LED, imaged through the 8X data relay to a detector at f/96 has the general form shown in Figure 4 and tolerances shown in Table 4. It can be seen that this system is very similar to the image mover system depicted in Figure 1 and summarized in Table 1. The LED simply replaces the guide star as a light source in the region behind f/12.

The difference in the two systems centers on the exchange of the optical image mover device for an internal 'star' source and some additional complexity in guidance electronics. There seems no rational alternative for providing a guidance detector directly at the f/96 image plane. Certainly proven flight optical system experience suggests that this is a requirement (and this experience is with considerably less stringent stability requirements). The use of a light source introduces risk of failure. In both systems the problem of light scatter throughout the system must be given careful attention.

TABLE 2. ALIGNMENT STABILITY TOLERANCE DATA F/12 TRACKING

Ritchey-Chretien secondary decentration	±0.5 mm
Relay module decentration	±0.6μ
Relay module tilt	±0.06 sec
Relay primary mirror decentration	±0.3μ
Relay primary mirror tilt	±0.04 sec
Structure (image plane) motion	±5 μ

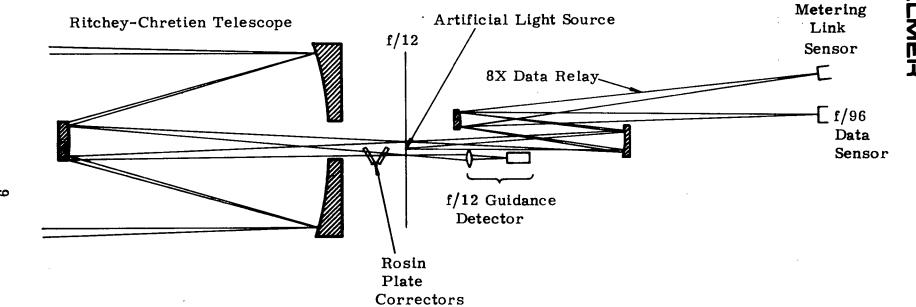


Figure 4. Ritchey-Chretien Telescope with Artificial Light Source

# TABLE 3. ALIGNMENT STABILITY TOLERANCE DATA F/12 TRACKING AND SEPARATE METERING LINK TO F/96

Ritchey-Chrétien secondary decentration	±0.5 mm
Relay module decentration	±0.6µ
Relay module tilt	±0.06 sec
Relay primary mirror decentration	±0.3µ
Relay primary mirror tilt	±0.04 sec
Structure (image plane) motion	±0.1 mm

# TABLE 4. ALIGNMENT STABILITY TOLERANCE DATA TELESCOPE SYSTEM WITHOUT IMAGE MOVER

Ritchey-Chrétien secondary decentration	$\pm 0.5 \text{ min}$
Relay module decentration	$\pm 12\mu$
Relay module tilt	1.5 sec
Relay primary mirror decentration	10μ
Relay primary mirror tilt	1-0 sec
Rosin plate angles	±0.02°
Structure (image plane) motion	±0.1 mm

#### SECTION II

#### STUDY DESIGN REQUIREMENTS

The LST Engineering Scale Model system will serve as the key tool for checking and evaluating system and technology innovations required to insure the high performance and long life of the 3 meter Large Space Telescope. MSFC has carefully defined the design parameters and objectives for this optical system design study based on the results of the recently completed LST Phase A study. The requirements define a basic telescope/relay system, two fine guidance concepts, coarse acquisition optics, and a window at the aperture of the telescope.

#### 2.1 TELESCOPE/RELAY

- f/12 Ritchey-Chretien telescope with f/2.2 primary of 1.2 meter diameter
- 8-power all reflecting relay
- Diffraction-limited imaging at both f/12 and f/96 5 min field at f/12, 2 min at f/96 wavefront error at f/96 less than  $\lambda/10$  rms
- Data sensor at f/96: integrating SEC Vidicon
- 36  $\widehat{\min}$  field of view with wavefront error less than  $\lambda/5$  rms
- Diffraction-limited performance and pointing stability as noted with secondary mirror articulated to compensate ±2 arc sec movement of telescope line of sight
- All-reflective design, minimum number of surfaces
- Modular construction; telescope and relay
- Provide back focal space sufficient to accommodate a focal plane figure sensor, spectrograph, automatic focus and filter wheel

- Length not to exceed 6.5 meters, diameter 1.8 meters
- Full aperture window to withstand differential pressure of 1/2 psia maximum.
- Coarse acquisition optics, 2° field of view

#### 2.2 FINE GUIDANCE SYSTEM

- Tracking field from 18 to 36  $\widehat{\text{min}}$ . diameter with rms image errors less than  $\lambda/5$
- Pointing stability to 0.008 arc-second over the ±2 arcsecond allowed telescope movement
- Tracking to utilize 30 arc-second diameter portion of tracking field
- Acquire and track on 12th magnitude star
- Modular construction
- Design need not be all reflecting, should consider reliability

#### SECTION III

#### OPTICAL DESIGN DATA

This section contains a description and details of the system optical design. In summary, the basic telescope is of the Ritchey-Chrétien form providing a diffraction-limited 5 min data field at the f/12 image plane. The central 2 min of the data field is relayed to f/96 by an all-reflective relay comprised of two off-axis portions of centered conic mirrors. Both relay elements are oblate spheroids. Length available was a key element in the selection of this configuration. Field corrector lenses are not used; instead the instantaneous 30 sec portion of the guidance field is corrected for astigmatism and field curvature by small flat tilted optical plates. Two fine guidance designs are considered; the first optically relays the guidance star through the entire system to a guidance sensor essentially integral with the data sensor. The second design provides for tracking at f/12 and an auxiliary metering loop to sense any movement of the instrument section of the telescope behind the f/12 plane.

#### 3.1 RITCHEY-CHRETIEN TELESCOPE

A pure Ritchey-Chrétien is defined by the four initial parameters:

Dp = primary mirror clear aperture = 1.2m

Fp = primary mirror focal ratio = 2.2

F = telescope system focal ratio = 12

B = vertex back focus, or working distance

The first three of these parameters have been defined by the baseline data upon which this detail design study is based. The only remaining parameter is the vertex back focus distance, B, and for this design it was chosen to be somewhere between 0.8m and 1.0m, in order that sufficient space would be available for later incorporation of fold mirrors and focal plane instrumentation.

The pure Ritchey-Chrétien form is now defined, geometrically (Table 5). A tabulation of the remaining derived parameters follows:

secondary mirror magnification - 5.45

system focal length - 14,400 mm

mirror separation - 2,099.2938 mm

primary mirror curvature - 1.9939410 x 10<sup>-4</sup> mm<sup>-1</sup>

(radius = 5,279.9952 mm)

primary mirror conic constant - 1.731380 x 10<sup>-2</sup>

secondary mirror curvature 7.5518867 x 10<sup>-4</sup> mm<sup>-1</sup>

(radius = 1,324.1724 mm)

secondary mirror conic constant -1.25475

vertex back focus 850.0024 mm.

The mirror sags are then defined by  $Y(r) = \frac{cr^2}{1 + (1 - Kc^2r^2)^{1/2}}$  in which c and K are the appropriate curvature and conic constants respectively, for the mirror in question.

Sag for each of the mirrors in the Ritchey-Chrétien are tabulated in Appendices A and B. These tables show, for 150 equispaced points along a mirror radius, the absolute sag from a reference plane containing the vertex and the sub-sag, being the difference between the aspheric mirror surface and a best fit reference sphere containing the vertex.

The telescope system is shown in Figure 5 which also indicates the size of the hole in the primary mirror as being 185 mm minimum diameter. Maximum primary mirror hole size is set by the requirement that it does not introduce a central obscuration greater than that already introduced by the secondary mirror. This sets a maximum hole size at approximately 280 mm diameter. That is, the minimum required clear aperture through the primary mirror hole is 185 mm diameter and the maximum primary mirror central obscuration diameter is 280 mm. The region between these two concentric diameters is available for baffling, mirror mounts, and other mechanical hardware.

In terms of achieving a data field image quality better than  $\lambda/10$  rms and a guidance field image quality better than  $\lambda/5$  rms, the Ritchey-Chrétien

# TABLE 5. RITCHEY-CHRETIEN OPTICAL DESIGN

OPTI	RKIN-EL	ONS DIVISION		LENS I	DESIGN	DATA SHE	ET		SHEET 1	of 1
3 PO /	<b>**0.</b>		DATE			RECOMP.			ESIGN NO.	
40	649/30,100			3/23/73						
EQU	IVALENT FOC	AL LENGTH	cr			MAGNIFICATION		OBJECT SPACE		
1	APERTURE	1003201	60			FIELD		0.3° se	mi-angular f	ield diam.
RATIO IMAGE SPACE F/					AND FORMAT IMAGE SPACE 150.32 mm					
		OBJECT TO	1MAGE			2,099.2938				
1	DISTANCES	FRONT VERT	850.0	ົ້າດ 24		FRONT VERTEX TO ENTRY PUPIL  0.0				
l	DISTANCES	BACK VERTE	EX TO IMAG	£ .		BACK VERTEX TO	EXIT PUP		0154	
Ì	•	FIRST PRINC	IRAL POINT	.2962	<del> </del>	SECOND PRINCIPAL	POINT	-503.34		
l			-456.	58.450987				-13549.	9 <b>972<b>7</b>5</b>	
370	At surfa	ce #1 - Pr	imary l	Mirror		STOP SIZE (AT MA	A. APERT	1199.99	9974	
TRA	ISMISSION					OBSTRUCTION RAT	10	0.233		
\$960	TRAL RANGE:	- MEG	. WAVELEN	GTH -		MIN. WAVELE	NGTH	-	·	IAR, WAVELENGTH
		<del></del>								
NO.	FIGURE	SURFACE	CLEAR	RADIUS	± TOL.	AXIAL	± TOL.		GLASS	1
	TOL.	NO.	APERT.			DISTANCE		TYPE	CODE	MELT NO.
	rms λ/64	1	1,2000 28010	-5279.99521	±5.0	-2,099.2938	±0_1	Mirror		ļ
,	*		268	-1.324.1724	±1.0	2,949,2962	**	Mirror		ļ
3		prime focus	150.32	, ,						l
-3-		roeus	110.12							
	(I)	Dadmons w	10-	eenheric - Co	onic co	nstant is -1	-7313	87.102		
		FIIMALY M								
	(2)	Secondary	mirro	r aspheric -	Conic	constant is	-1.25	475		<u> </u>
	*	Secondary	mirro	r is figured	to giv	e total syst	em pe	rformance	equal to or	better
		than $\lambda/20$	rms O	PD					l l	
		7.,				′				
	**	This dist	ance 1	n the back fo	ocus					
								İ		
								<u> </u>		
_										
· <del></del>										

NOT REPRODUCIBLE

Figure 5, Ritchey-Chretien Ray Trace

telescope system should be figured to provide no more than  $\lambda/25$  rms wavefront error over the central 2 min field and no more than  $\lambda/15$  rms wavefront error in the 18 min to 36 min annular guidance field.

Aberrations in an optical imaging system are manifest as a spread in the points of intersection of rays from different points in the pupil with the focal plane. Thus, the quality of an optical system may be visualized readily by the lateral aberration curves shown in Figure 6. In these curves, for a given field angle, the ray height at the focal plane is plotted against the pupil radius that ray passes through - normalized to a full pupil radius of 1.0. In such a presentation, a perfect system exhibits a straight line parallel to the abscissa. An out of focus condition is represented as a straight inclined line and aberration as various forms of curvature to the line.

#### 3.1.1 Effects of Articulated Secondary

A true Ritchey-Chrétien telescope, correctly manufactured and aligned, is completely free of third order coma. The chief residual design aberrations are astigmatism and field curvature. However, when the secondary mirror is tilted somewhat, to correct for a telescope mispointing of up to 2 arc-sec, this introduces a small amount of axial coma - the effects of which on the fine pointing system performance are worthy of study.

Assume that the fine guidance sensor operates as a four quadrant device, achieving a null condition by balancing the incident energy received by each of the four quadrants. In this manner, the fine guidance head will lock onto the median point of the guide star image; defined as that point through which any straight line will divide the image plane guide star energy into two equal parts. For an image from a perfectly aligned telescope this point corresponds to the position of peak intensity and also to the geometric center of the Airy Disc.

However, for off-axis images when the secondary is tilted, each of these points - the geometric center, position of peak intensity and median point-are separated by small amounts. This separation is of no consequence to the offset guide star tracking concept provided that if the secondary mirror is tilted to compensate for a maximum mispointing, no unacceptable change in separation of these points occurs.

To determine what constitutes an unacceptable change in this separation, the stability of the data star image must be considered. When the secondary mirror is tilted to compensate for 2 arc-sec telescope mispointing, the energy within the Airy disc of the data star image suffers approximately the same redistribution as does the guide star. This might be expected since the

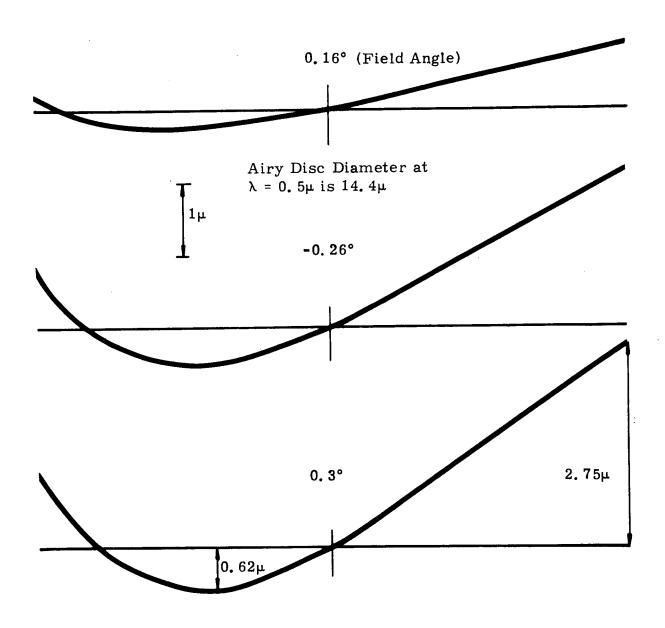


Figure 6. Ritchey-Chretien Telescope, Lateral Aberration Curves

coma introduced by tilting the secondary is field independent. This energy redistribution does in fact give rise to a small shift in the position of the first dark ring on the image plane. This shift must also be taken into account in considering the effects of articulating the secondary.

The position of the guide star image median point was computed for a guide star 18 arc-min off-axis with the secondary mirror in its perfectly aligned condition, and then again with the secondary mirror fully tilted to compensate for 2 arc-sec telescope mispointing. The resulting change in the position of the median point is  $0.6\mu$ .

Also, the motion of the data star image was found by computing the displacement necessary to maximize the energy passing through a fixed image plane aperture the size of the Airy pattern first dark ring. This was found to be approximately 0.55  $\mu$  to 0.58  $\mu$  in the same direction as the guide star median point shift.

The difference, then, between guide star median point shift and data star image shift is of the order of 0.05  $\mu$  or less. Compared to a design goal of fine guidance to within 1/10 Airy disc diameter, or 1.5  $\mu$ , this is insignificant.

Thus, it may be concluded that, using a tracking scheme which follows the guide star image median point, and defining the optimum position of the data star as that which maximizes the energy passing through a fixed aperture the size of the first dark ring, articulating the secondary causes no undesirable effects for up to 2 arc-sec telescope mispointing.

Although it is true that the small amount of coma introduced by tilting the secondary could be removed by a small decentration of the secondary (i.e., by tilting the mirror about some point behind it), the amount of coma introduced is very small, and does not appear to be significantly degrading in performance to warrant the considerable additional mechanical complexity of articulating the secondary about a point other than its center of gravity.

The foregoing argument is equally valid if an image dissector is used as the tracking error detector rather than a four quadrant divider, since most of the proposed image dissector scan patterns rely on a certain symmetry to the guide star image energy distribution.

#### 3.2 8X DATA RELAY

Prior to the detail design of the 8X Data Relay, a preliminary investigation was performed in order to determine the precise form of relay best suited to the system. An on-axis form would have obvious advantages in terms of symmetry, ease of mounting, manufacturing and alignment, but would be appreciably longer than a corresponding off-axis design, due to the constraint that the relay should introduce no additional central obscuration beyond that already present in the Ritchey-Chrétien telescope design.

As a result of this preliminary study (Perkin-Elmer Report No. 11378), it was concluded that an on-axis form was not possible within the constraints of total length limitation and the performance requirements. An off-axis design was therefore pursued in detail (Figure 7).

The detail design of the two element off-axis relay system is summarized in the lens design data sheet, Table 6.

Each mirror is an off-axis section of an oblate spheroid; both mirrors being aligned co-axially. The optical axis of the relay system is parallel to, but displaced 20.7 mm from, the Ritchey-Chrétien optical axis.

The relay design, itself, introduces no obscuration. The central obscuration listed in the design data sheet is that due to the Ritchey-Chrétien telescope. Assembly/alignment tolerances for this relay design are shown in Table 7. This table has been divided into two parts: one providing initial assembly tolerances, allowing focus adjustment, and the other providing a set of stability criteria which must be met in order to preserve optimum performance over a long time interval, without adjustment.

The 12.7 mm object field diameter corresponds to a nominal 3 arc-min telescope data field at the Ritchey-Chrétien f/12 image plane. The relay magnification is 8X, so this object field is presented as a 102 mm diameter image field at f/96 to the data sensor.

The relay system has been designed to accommodate a 3 arc-min field rather than the required 2 arc-min field in order that the same optics may simultaneously relay the guide star images just outside the data field, when used in conjunction with an image mover tracking scheme.

The worst case rms optical path difference at the edge of the 3 arc-min field is less than  $\lambda/10$ , and the optical performance is significantly better than this over the central 2 arc-min data field.

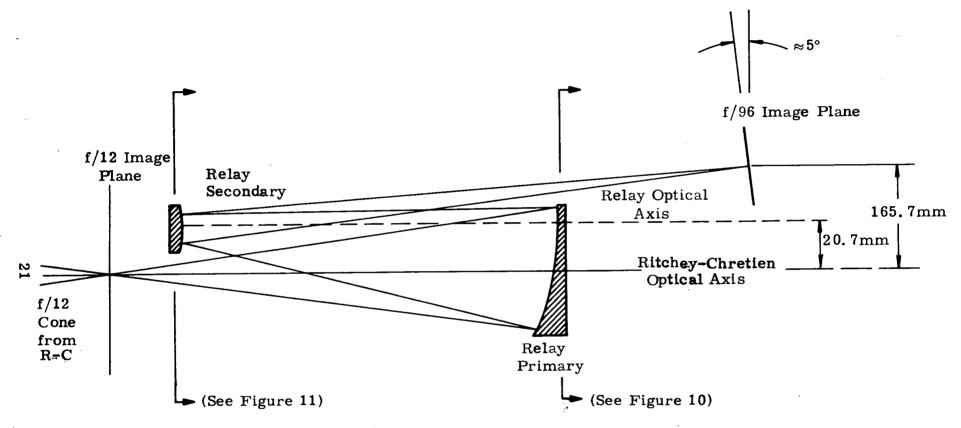


Figure 7. .8X Data Relay - Optical Schematic (not to scale)

# TABLE 6. 8X DATA RELAY DESIGN

PTI	RKIN-EI	NOISIVID SHOL	•		- / -	DATA SHE			SHEET	1 0, 1
100 I		DANECTICOT	DATE			TRECOMP.			DESIGN NO.	
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EQUIVALENT FOCAL LENGTH					MAGNIFICATION		OBJECT SPACE			
		OBJECT SPACE F/		FIELD		12.7		20.7		
	APERTURE RATIO					AND FORMA	T	IMAGE SPACE	mm off axis	
			96		FRONT VERTIX TO	BACK V	C 9 7 C 2		103.5	
OSJECT TO			301	1.6	·		1478	.3	<del> </del>	
	DISTANCES	FRONT VERT	140	4.2		FRONT VERTER TO	ENTRY	-5052	•2	
		BACK VERTO		t		BACK VERTEX TO	EXIT PU	-1708	-1	
		FIRST PRINC				SECOND PRINCIPAL	POINT			
		FIRST PRINC	-116	3.7	<del></del>	STOP SIZE (AT MA		-2147	•0	<del></del>
310P	POSITION	-		•				•		
TRAN	SMISSION			·		DESTRUCTION RAT	'° 0	.3 from R	itchey-Chreti	len
SPEC	TRAL RANGE:					<del></del>				<del> </del>
	<u> </u>	MED	. WAVELEN	G TH		MIN. WAVELE	NGTH			MAX, WAVELENGT
	FIGURE	SURFACE	CLEAR	· · · · · · · · · · · · · · · · · · ·	r	AXIAL		T	GLASS	
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1	1/20	120=70	_(1)	-1743.6 (3)	-0 +8	1607.4		Mirror		
2	*	80-50	(2)	-1001.9(4)	-5 +0	-1478.3	l .	Mirror		
-		00-50	1 50/	<b>&amp;</b>		2882.5		Back f	ocus	
-						200213				
$\dashv$	(1)	151 0 14		/: EE 2 ha	06 6		-			
-	(1)			(+55.3 to -			<del> </del>			
_	(2)	37.5 dia	meter	(+33.2 to -	4.3)				<u> </u>	<del></del>
				i 						
	(3)	conic con	stant	E = +1.06974	5 - x =	x spherical	- 1	.64458(10	$^{-12}$ ) $Y^4$ (AX	$= 0.143 \mu$
	(4)	conto con	atant	E = +4.96659		v enherical	- 4.	93008 (10	-10) y <sup>4</sup> (AX	= 0.606µ
		eonie eon	Scanc	E = +4.30033		x splicifical		1 (20	PI	) - 0.000p
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TABLE 7. STRUCTURAL AND ALIGNMENT TOLERANCE SUMMARY

	Structural Stability Tolerances					Initial Alignment Tolerances	
	Tolerance	Resulting rms OPD µ	ΔH' Axis	Deviation	Tolerance	Resulting rms OPD μ	ΔH' Axis
		0. 032	0.0	None Nominal Design		0.032	0.0 mm
	0.3 µ	0, 032	5μ	Decenter Primary with respect to secondary	± 0.2 mm	0.051	+ 2.96 mm
23	±0.04 sec	0.032	5μ	Tilt Primary with respect to secondary	± 1 arc- min	0.058	+ 7.53 mm
w	±0.01 mm	0. 032		Separation between primary/secondary	± 0.05 mm	0.062	

These tolerances assume that the guide star image is not relayed by the data relay mirrors. They will be significantly increased if this is eventually the case: -

The relay also relays guide star image,

±7μ	100μ	Decenter Primary with respect to secondary optical axis
±1 arc-sec	100μ	Tilt primary with respect to secondary optical axis

Field distortion over the 2 arc-min data field corresponds to 0.003 arc-sec in object space and this deteriorates in the region between 2 arc-min and 3 arc-min to approximately 0.015 arc-sec in object space.

Considerable effort has been expended during the course of this design to keep field distortion within acceptable limits. Such distortion has been considered highly undesirable in the 2 arc-min data field especially for viewing extended objects. Such known distortion as would be introduced by the relay system, however, could be removed by electronic data processing of the final image - something that will in all probability be done, anyway. Electronic processing of the final image was not an initial condition of this design effort, however, and so has not been assumed. Obviously, if such processing is adopted, then the relay system could be simplified in form.

The relay system lateral aberration is shown in the lateral aberration curves, Figure 8, and distortion characteristics in Figure 9. The clear apertures required by the folded design are shown in the plane of each of the mirrors in Figures 10 and 11.

#### 3.3 OFFNER-ROSIN PLATE CORRECTORS

Based on Rosin's original proposal<sup>1</sup> of a pair of inclined plane parallel plates for local correction of field astigmatism in a Ritchey-Chrétien telescope, this adaptation - due to Offner - employs four such plates, so designed as to correct for astigmatism and field curvature.

One pair of plates tilts in the tangential direction, the other pair in the radial direction. By proper choice of plate thickness for each pair, a given tilt angle can be made to provide the optical path correction necessary for both astigmation and curvature of the field.

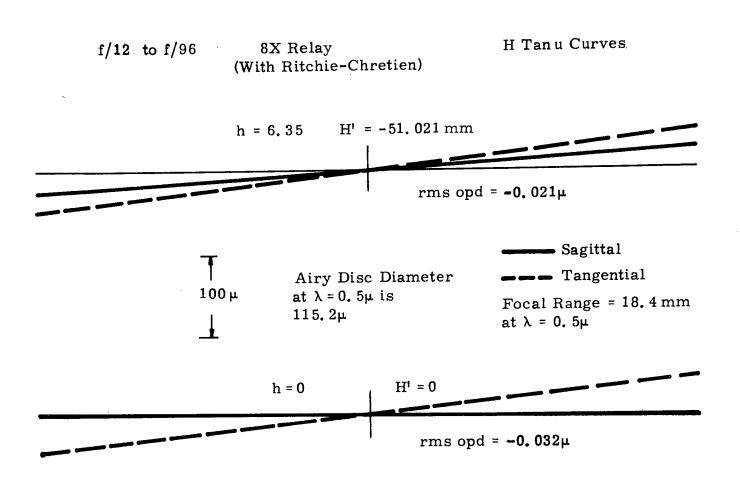
In the case of this design, the relevant plate thicknesses are:

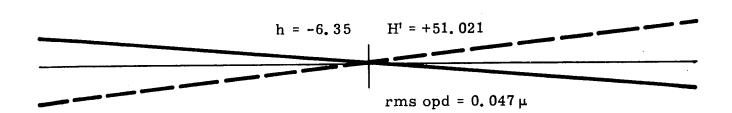
Tangential plates, each 10,663 mm of fused silica N = 1.4585

Radial plates, each 7.440 mm of fused silica N = 1.4585

The angle of inclination of the plates necessary to achieve full correction will vary from close to 0° to approximately 45°, depending on field position, as shown in Figure 12. Once set, this angle must be stable to within  $\pm 0.02^{\circ}$ , and tilt stability in the direction along the pivot axis must be within  $\pm 0.06^{\circ}$ .

<sup>&</sup>lt;sup>1</sup>S. Rosin and M. Armor, Appl. Optics <u>11</u>, 7, (1972)





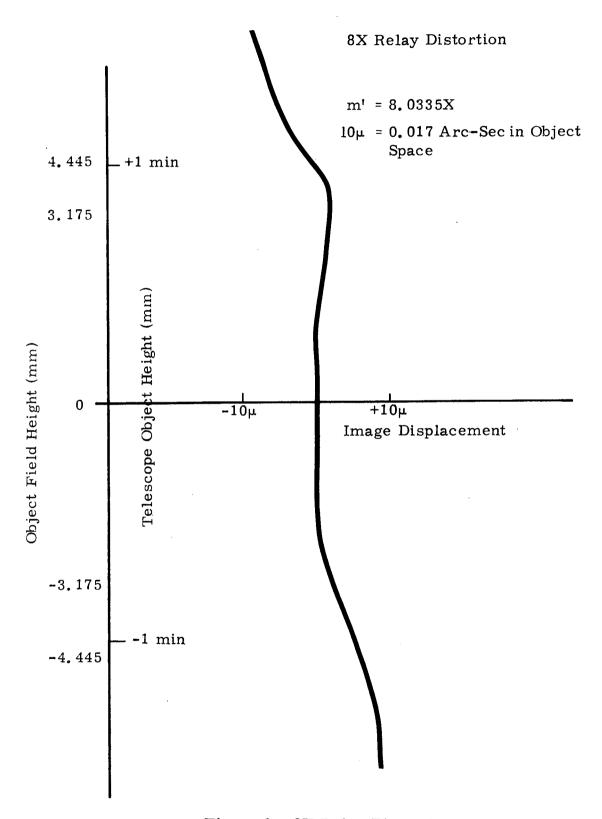


Figure 9. 8X Relay Distortion

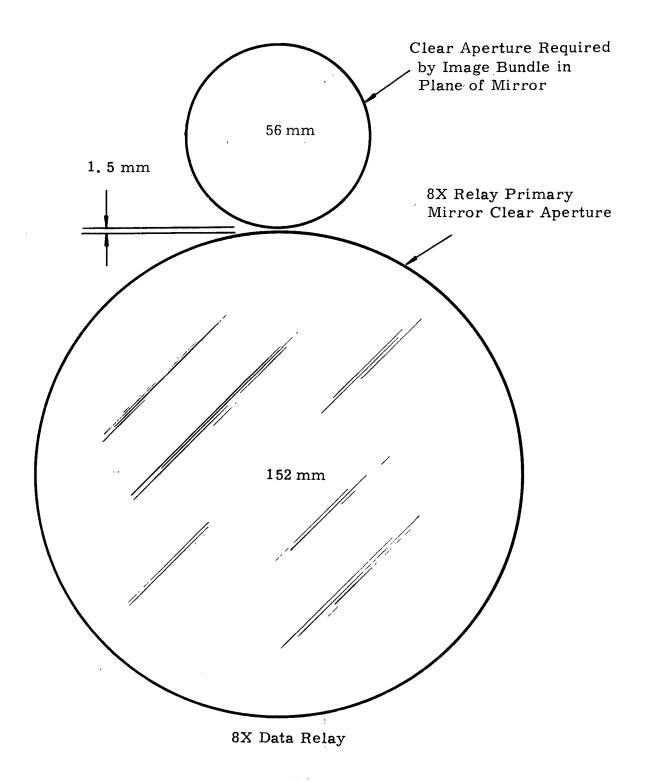


Figure 10. Relay/Primary Clear Aperture

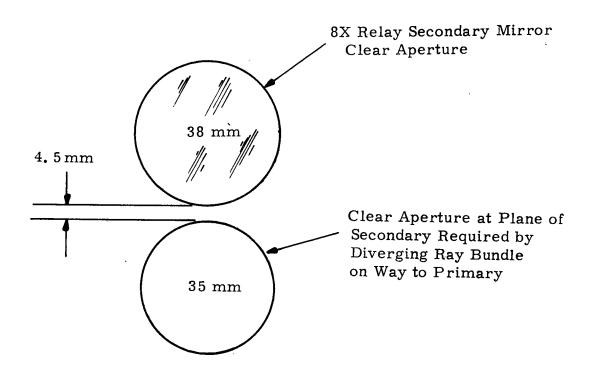


Figure 11. Relay/Secondary Clear Aperture

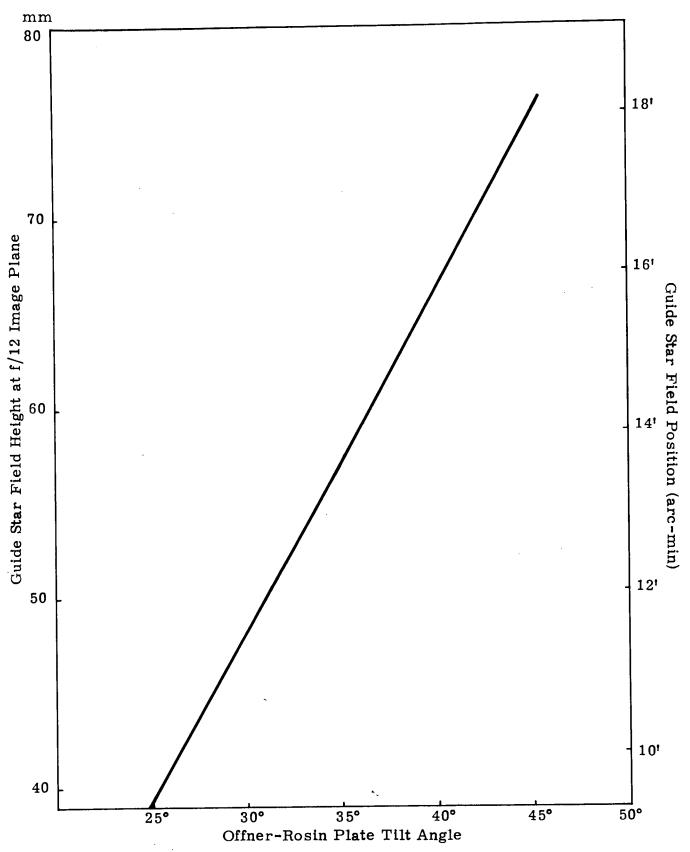


Figure 12. Offner-Rosin Plate Required Tilt Angle

Since the Offner-Rosin plate assembly requires a mechanical rotation input which is a function of field position, it lends itself to incorporation into the front end of an image mover assembly (paragraph 3.4). That assembly also requires a shaft rotation which is a function of field position. Preliminary layouts indicate the two systems to be very compatible. The Offner-Rosin plates themselves used in this manner, are quite small, requiring clear apertures of only about 10 mm diameter. To account for obliquity factors, therefore, the largest plate should be approximately 30 mm in diameter. The OPD of each plate, in transmission, should be  $\lambda/10$  rms and wedge angle within the plate should not exceed 1 arc-min.

#### 3.4 IMAGE MOVER

The fundamental element of the tracking scheme is the image mover, which is designed to intercept the converging f/12 bundle of a guide star image and relay it, at unity magnification, to a fixed output point just inside the field of view of the data relay (but outside the data field).

In this manner, the guide star is relayed to the f/96 plane by the same optical elements as the data star, and tracking is achieved through the whole system. The only elements not common to data and guide star channels are the elements of the corrector plates and image mover elements themselves. Since these are small elements, in a compact package, their stability is more easily controlled.

The image mover is comprised of a negative lens, articulated in such a manner as to be able to locate a guide star within the guidance field, fold mirrors or prisms, and a refocusing lens at the fixed output axis. The negative lens collimates the f/12 bundle. This collimated bundle is then folded into the axis of the positive element, positioned so that the output f/12 bundle falls just within the data relay field of view (Figure 13). To account for the field angle of the chief ray in the f/12 bundle the negative element will, in general, work slightly off-axis. However, by proper choice of focal lengths, the negative lens axis has been made always to pass through the nominal guide star image position in the telescope f/12 image plane. This is shown in an exaggerated sense in Figure 14.

The detailed design of the image mover lenses is summarized in the lens design data sheet, Table 8.

Since the image mover is an optical system of unity magnification, the output cone chief ray is parallel to the input cone chief ray. That is, the field angle is unchanged by the image mover. Thus, although the guide star image is translated by the image mover system to a point just within the field of the data relay, the field angle of the emergent guide star ray bundle is

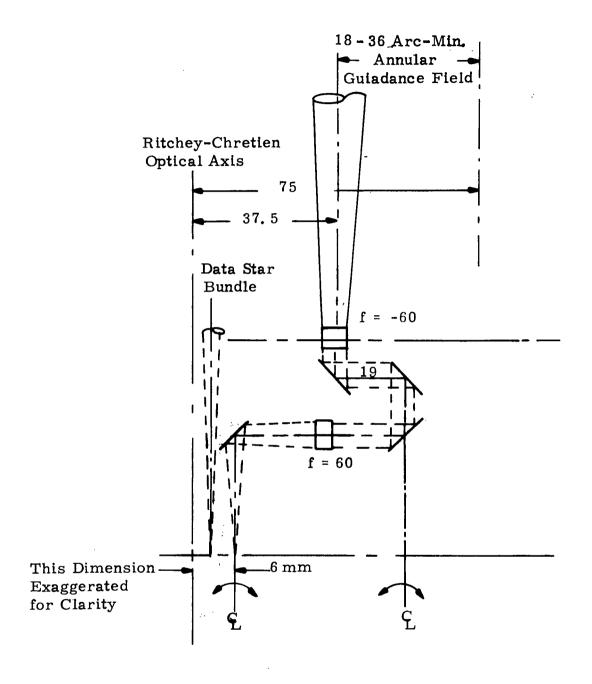


Figure 13. Image Mover Optical Layout (Full Scale)

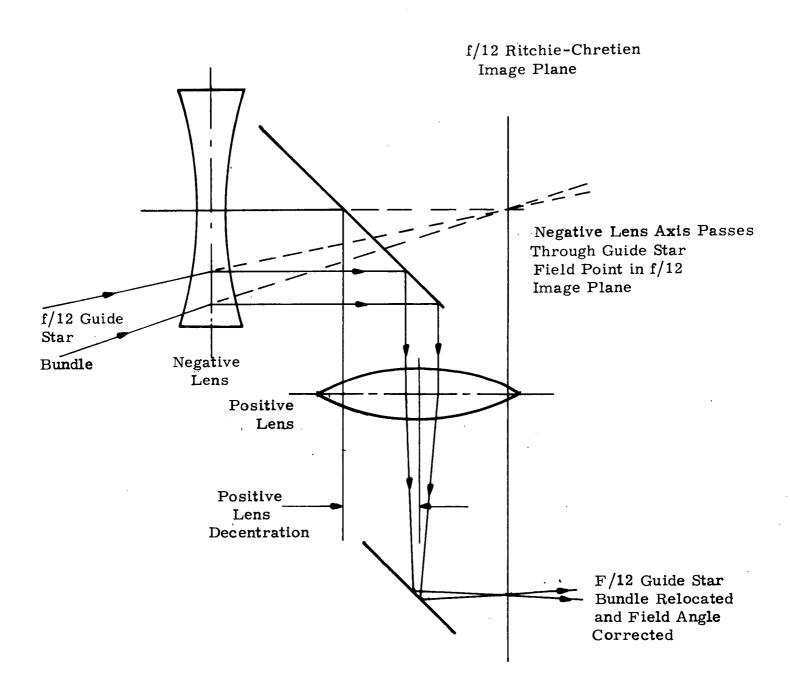


Figure 14. Image Mover Lens Decentrations

TABLE 8. IMAGE MOVER DESIGN

3F	RKIN-E	MER		LENS	DESIGN	DATA SH	EET			
PTIC		IONS DIVISION								1 or 1
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QUI	VALENT FOO	AL LENGTH	46.57			- ALONIFICATION	10	SIECT SPACE		
	APERTURE		12 IMAGE SPACE 7/ 12			FIELD		0.5 arc	-min_full	field
	RATIO	IMAGE SPA				AND FORM				
		001 103180	80.5			FRONT VERTIA	TO BACK VER	86.2		
		FRONT VER	TER TO IMAG	C		PRONT VERTEX	TO ENTRY PU	PIL		
	DISTANCES	BACK VERT	143.			BACK VERTER T			<u> </u>	
		1	56.8	·	<del></del>		PAL POINT	104.2		
		PIRST PRIN	62.7					57.0	· · · · · · · · · · · · · · · · · · ·	
TOP	POSITION					STOP SIZE IAT	MAZ, APERT.	, 		
FAN	5M15510H					GESTRUCTION R	ATIO			
· PEC	TRAL RANGE:	5876 ws	O. WAVELEN	avul	4861	MIN, WAYE	LENGTH !		6563	MAT. WAVELENG!
					4002					
0.	FIGURE	SURFACE	CLEAR	RADIUS	± TOL.	AXIAL DISTANCE	± TOL.	TYPE	GLASS	MELT NO.
	TOL.	HO.	APERT.			DISTANCE		TTPE	1 2002	MELT NO.
1	λ/8	60-40	6.6	-172.55	2λ	2.0	0.1	F4	NH1	<u> </u>
2	λ/2	60-40	6.6	-25.349	2\	3.0	0.1	BK7	NR1	
3	λ/8	60-40	6.6	30.137	2λ	76.2	0.2	AIR		
4.	λ/8	60-40	6.4	29-997	2λ	3.0	0.1	BK7	NH1	
5	λ/2	60-40	6.4	-23.61	2λ	2.0	0.1	F4	NH1	
6	λ/8	60-40	6.4	-163.492	23.	56.8		! 	<u> </u>	
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exactly the same as for the undisturbed guide star image - which will in general be somewhere between 9  $\widehat{\min}$  and 18  $\widehat{\min}$ . This means that the relay mirrors will have to be of sufficient aperture to accommodate this field angle. What would, for data purposes only, be an f/12 relay will in fact have to be an f/10 relay if it is also to carry a guide star image from a simple image mover.

To change the present relay design from f/12 to f/10, would mean that the relay mirrors would then work further off-axis, increasing the resultant distortion. To reduce the distortion to acceptable limits would require a longer relay, and/or more aspheric surfaces.

Such a complication to the present relay system design (paragraph 3.2) has been deemed unacceptable, and an alternate solution is here proposed.

The field angle of the emergent bundle may be controlled, without unacceptable image degradation, by decentering the final positive lens element to the image mover. The actual decentration amount is dependent upon the guide star field position, but for 18 arc-min would be approximately 1.25 mm (Figure 14). Such a programmed decentration could be built into the image mover mechanics with little additional complication. The only real problem with such an approach is that it introduces one more moving component, which must be locked with high stability for the duration of an exposure.

As mentioned in paragraph 3.2, if electronic data processing of the final image is adopted, the relay lens can be designed with no great difficulty to accommodate the guide star field angle without the added complexity of decentering the image mover positive lens.

The prime causes of instability during an exposure are expected to be lens tilt or lens decentration due to a changing thermal environment. Such tilts must be controlled to be within  $\pm 0.5$  arc-secs for each lens, and decentrations to within  $\pm 0.5 \,\mu$ .

### 3.5 F/12 GUIDANCE

This is an alternate to the image mover tracking concept involving separation of the data and guide star optical paths. The corrected guide star image is received at the flattened f/12 image plane and magnified by an 8X refractive relay and presented to the detector device; either four quadrant divider or image dissector tube. Relative motion between the f/12 image plane, where tracking is performed, and the f/96 plane, where data is gathered, is monitored by a separate internal metering system.

#### 3.5.1 Relay Lens Design

The detail design parameters for this lens, a four element group, are presented in lens design data sheet, Table 9. The magnification is 8X, so that tracking is performed on an f/96 image, but the lens itself is compact so that the physical location of the tracking detector is close to the f/12 prime image plane. This catalog design has been color corrected for the spectral region 5,000Å to 6,000Å. Correction could be modified to other spectral regions, if necessary, depending upon the spectral sensitivity of the photocathode material eventually used. The lens group layout is shown, to scale, in Figure 15.

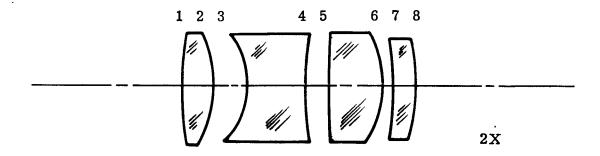


Figure 15.. F/12 Guidance Relay Lens

TABLE 9. REFRACTIVE RELAY DESIGN

TUO	H WILTON, C	ONNECTICUT				•			SHEET_	1 or 1
<b>▶ P 0</b> <i>Z</i> •			DATE			RECOMP.		D	SIGN NO.	
	649/30			3/23/73		MAGNIFICATIO	<del></del>			
EQUI	VALENT FO	OBJECT SP	ACE F/			MAGRIFICATIO		OBJECT SPACE		
APERTURE RATIO			12			FIELD	-	MAGE SPACE		
		MAGE SPACE F/				AND FORMAT				
		08,507 10	337.	7580		FRONT VERTIX TO	29.4	6	•	
	DISTANCES	FRONT VER	322.			FRONT VERTEX TO	0.0	JPIL		
	DISTANCES		EX TO IMAG	(		BACK VERTEX TO	EXIT PUP	001665		
		FIRST PRIN	CIRAL POINT	234768		SECOND PRINCIPA	L POINT	991465		
		1	22.9	92198		STOP BUTE IAT N		208232		
BT0P	0.0 fro	m surface	#1			STOP SIZE (AT M				
TRAN	5W15510H					0.3 from	Ritche	y-Chertier	1	
S PC C	TRAL PANGE:	5,500 ME	0		5,000	MIN. WAVEL		·	6,000	MAX. WAVELEY
		2,500 M			-,				- 1	
10.	FIGURE	SURFACE	CLEAR	RADIUS	± TOL.	AXIAL	± TOL.		GLASS	
<u>"  </u>	TOL.	NO.	APERT.			DISTANCE 15.0632		AIR	CODE	MELTH
1	$1/4\lambda$	80-50	1.26	51.0874		3.9		I.AF22		
2	1/4λ	80-50		-17.1057		4.93		ATR		
		80-50				7.00		SF11		
3	1/4λ			-9.4325	-		<u> </u>	1		
4	<u>1/4λ</u>	80-50	T	37.8913		2.35	+	AIR	<del></del>	
5	1/4\	80-50	4.57	101.0730		7.00	<del> </del>	BK50	<u> </u>	
6	1/4λ	80-50	6.24	-14.9904		0.93		ATR	<u> </u>	
7	1/4λ	80-50	6.43	-114.9479		3.35	L	SK16		
8	1/4λ	80-50	6.82	-26.3903		293.2348	]	AIR		
9			17.28					c.		
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#### 3.5.2 Internal Metering System

A simple and reliable metering concept employs a small light emitting diode, a fast relay lens and a detector (in the form of an image dissector or four quadrant phototube). The single element relay is used to produce a circular far field pattern at the detector head. Its design is very straightforward since it is required to operate monochromatically. A lens of 15 mm focal length and f/2 will be adequate.

#### 3.6 WINDOW

If a window is used at the entrance to the telescope system, its optical properties are of great significance since all other optical elements follow it and operate on the incoming wavefront as aberrated by the window.

Any tolerance on wavefront deviation ascribed to the window, then places more stringent specifications on all succeeding elements by using up part of the overall allowable error budget. For purposes of this study, the window has been allowed 1/50 wave rms OPD and up to 1/4 wave spherical power. (Power can be removed by a small focus adjustment.) Its thickness must be such as to maintain these tolerances in the presence of whatever operational pressure difference might be applied. The diameter of the window should be such that a minimum clear aperture of 1.25 m is available.

#### 3.7 BAFFLES

Experience gained with other comparable optical systems has demonstrated the very significant gains in performance possible from extensive stray light suppression schemes. The diversity of instrumentation and astronomical application planned for LST will benefit greatly from the implementation of such a scheme and from its development and proving on the LST engineering technology model.

However, a detailed baffle design cannot be undertaken until all telescope instrumentation, including alignment, focus and figure sensors, have been designed and their integration into the LST defined.

#### 3.8 COARSE ACQUISITION CAMERA

The coarse acquisition camera will be used as the coarse field aiming device, just as a guide telescope is used to aim a ground based telescope. It is required to view a 2° diameter field, and to be boresighted to the line of sight of the main telescope.

The image field of the coarse acquisition camera is to be received by an image orthicon or similar TV system. In the absence of more detailed information on the proposed TV system, the lens has been designed as a 2° field, f/4, diffraction limited Catadioptric - color corrected over the broad spectral region from 4047Å to 7000Å.

The design details of the lens are shown in lens design data sheet, Table 10, and a schematic layout of the assembly in Figure 16. This particular catadioptric form of design was chosen since it is easiest to compensate chromatically over a wide region, and results in a rugged, compact design which is both simple and economic to manufacture, since all the optical surfaces involved are purely spherical.

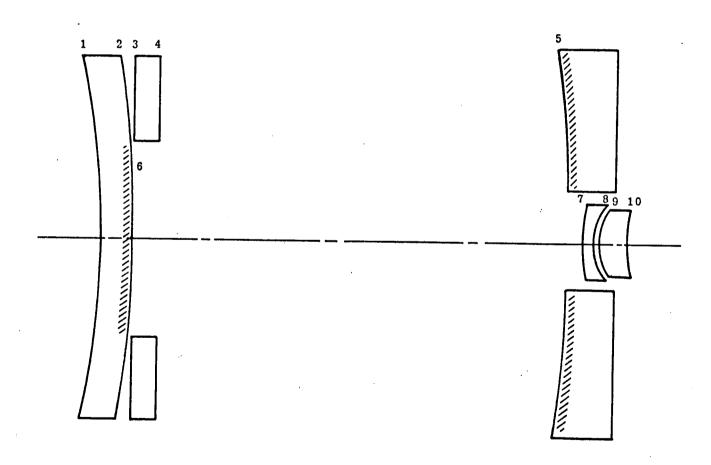


Figure 16. Coarse Acquisition Camera Lens - Optical Layout

# TABLE 10. COURSE ACQUISITION CAMERA DESIGN

DE	RKIN-EI	MER		LENS	DESIGN	DATA SHE	ET			
OPTI	CAL OPERAT!	HOISIVID 2HO							SHEET .	l or1
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350	~°. 649/30		1	3/23/73						
EQU	IVALENT FOC	AL LENGTH				MAGNIFICATION	- 12	BJECT SPACE	i-angular f	
	APERTURE	∞ .								leld
1	RATIO	IMAGE SPA	IMAGE SPACE 4			AND FORMA			m diameter	
		08/557 70	IMAGE .			FRONT VERTIX TO				
	DISTANCES	FRONT VER	TEX TO IMAG	E		FRONT VERTEX TO	0.0	PIL		
	DISTANCES	BACK VERT	EX TO IMAG			BACK VERTER TO	EXIT PUPI			
		PIRST PRIN	30.0			SECOND PRINCIPAL	L POINT			
170	POSITION					STOP SIZE (AT M	AX. APERT	.)		
l	0.0 from	n surface	#1			OBSTRUCTION RAT	110			
ŀ						•	0.46			
3966	TRAL RANGE:	5,461 me	D. WAVELEN	тн	4,047	MIN, WAVELE	NGTH		7,682	MAX, WAVELENST
_		SURFACE	CLEAR			AXIAL	± TOL.	T -	GLASS	
но.	FIGURE TOL.	NO.	APERT.	RADIUS	± TOL.	DISTANCE	I TOL.	TYPE	CODE	MELT NO.
1	1/2λ		125.3	-266.160	1	10,15	±0.0	1 BK-7		
2	1/2λ		127.1	-399.289		0.0	±0.0	1 AIR		
3	1/2λ		127.9	844.465		9.13	±0.0	1 BK-7	· ·	
4	1/2λ		128.1	8		143.86	±0.0	1 AIR		
5	1/4\		133.3	-503.438		-153.00	±0.0	1 AIR		
6	1/4λ		57.8	-399.289		156.41	±0.0	1 AIR	<u> </u>	
7	1/2λ		25.3	54.713		4.06	±0.0	1 BK-7		
8	1/2λ		23.3	17.733		0.36	±0.0	1 AIR		
9	1/2λ		23.4	18.038		8.73	±0.0	1 BK-7		
10	1/2λ		21.7	40.518		30.04	±0.0	AIR		
11		image pla	ne 15.8	₩						
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#### SECTION IV

#### SYSTEM TOLERANCE ANALYSIS

The LST will provide a wide range of instrumentation capability over an extended lifetime and will require flexibility for instrument checkout, repair and replacement. The concept of modular design should greatly facilitate attainment of these objectives. To the extent possible, each subsystem should be self-contained and qualificable prior to its assembly into the LST system.

The LST Engineering Scale Model is specified to follow the modular concept. As shown in Figure 17, the system is composed of four basic sections (or modules):

- 1. The Ritchey-Chrétien telescope objective (including the aperture window)
- 2. The eight power reflective data relay
- 3. Fine Guidance Optical System
- 4. Coarse Acquisition System

In analyzing the system tolerances for inter-modular alignment errors, all other modules are referenced to the Ritchey-Chrétien optical axis for tilt and decenter errors and to the Ritchey-Chrétien primary mirror vertex for axial position tolerances. The design specification requires that the data wavefront at f/96 have a wavefront error no greater than  $\lambda/10$  rms. The basic optical data elements, the primary, secondary mirror and eight power relay have been designed and toleranced such that the system, when perfectly aligned, will provide an OPD at f/96 not to exceed 0.032  $\lambda$  rms. It will be shown that system alignment and structural stability tolerances (between modules) will be much influenced by the design of the fine guidance system.

The optical element fabrication tolerances and the intra-modular assembly tolerances for both the R/C telescope and the eight power relay are given in Tables 5 and 6. Each is separately assembled, aligned and tested.

Figure 17. System Module Identification

The key module interface is the positioning of the relay relative to R/C and for this purpose the point of reference on the relay assembly has been defined to be the relay secondary mirror vertex. Although great convenience is derived from thinking of the relay as a separate module, the system tolerance analysis must consider the basic philosophy of LST operation and in this sense the relay tolerances become heavily dependent upon the precise form of the fine guidance system.

Due to its high magnification, the relay assembly must be held very accurately centered and aligned in order that it shall not introduce instabilities in the data star image position over an exposure period. However, if the guide star is also relayed by the same optical elements as the data star, then the fine guidance system will be able to track through the whole telescope optical system and thereby remove small, low frequency disturbances in the relay assembly or instrument support structure. The relay module stability tolerances then become less stringent.

Table 11 defines the tolerances on (1) centering of the relay assembly with respect to the R/C axis and (2) tilt of the relay assembly axis with respect to the Ritchey-Chrétien optical axis. Tolerances are given, for both fine guidance concepts, for initial alignment of the telescope system and for allowable stability shifts before performance degradation is introduced.

In this study, two particular kinds of performance degradation were considered, and the tolerance assigned on the basis of the more sensitive of these. First was wavefront error, at the data image plane, and second was displacement of the data star image at the f/96 image plane, or image motion. In all cases, the more limiting sensitive performance criterion was image motion. When stability tolerances are assigned on the basis of controlling image motion to acceptable levels, there is no measurable change in wavefront error from the nominal design amount of  $0.032\mu$ . It is clear that structural stability requirements are much affected by the guidance concept.

#### 4.1 IMAGE MOVER - ROSIN CORRECTOR ASSEMBLY

This movable optical assembly serves to relay (at unity magnification) the guide star to a fixed point at the edge of the data field. It is the single element which is not common to both data and guidance optical paths. Positioning of the image mover assembly relative to the Ritchey-Chrétien is dependent on the accuracy to which a coordinate system needs to be referenced for purposes of locating a guide star by remote control. Thereafter, stability is the prime and critical requirement. The assembly should be stable such that the output converging bundle does not translate more than  $\pm 0.5 \,\mu$  or tilt more than approximately  $\pm 0.1$  min. during the period of an exposure (this could be up to 10 hours in LST).

TABLE 11. RELAY SYSTEM TOLERANCES

GUIDE STAR NOT RELAYED BY DATA RELAY							
Stru	Structural Stability Initial Alignment Tolerance						
Tolerance	Resulting rms OPD µ	ΔH' Axis	Deviation	Tolerance	Resulting rms OPD µ	∆H' Axis	
	0.032	0.0	None Nominal Design		0, 032	0.0	
0.6µ	0.032	±5μ	Decenter relay WRT R/C axis	±0.1 mm	0.040	±0.8 mm	
0,06 arc-sec	0.032	±5μ	Tilt relay about its secondary mirror vertex	±30 arc- sec	0.040	±0.7 mm	
		GUID	GUIDE STAR IS RELAYED BY DATA RELAY				
±12μ	0. 032	100μ	Decenter relay WRT R/C axis	±0.1 mm	0.040	±0.8 mm	
±15 arc-sec	0.032	100μ	Tilt relay about its secondary mirror vertex	±30 arc- sec	0.040	±0.7 mm	

#### 4.2 ROSIN CORRECTOR - RELAY AT F/12 ASSEMBLY

The Rosin corrector-relay assembly for guidance in the f/12 focal plane is integral with the guidance detector. Similar to the image mover assembly above, its positional accuracy is dependent on the precision of the coordinate system used to locate the selected guide star. Thereafter, the stability of the assembly is critical and should be stable to better than 0.1 Airy disc diameter. Thus, the tolerance in the f/12 plane for translation will be  $\pm 0.5 \,\mu$  (1/30 Airy disc) and tilt shall not exceed  $\pm 0.1 \,\mu$  min.

#### 4.3 F/12 TO F/96 METERING LINK

The components of the metering system (LED, relay and detector) used to monitor relative motion between f/12 and f/96 planes are small, compact, and should be monitored so as to be mechanically integral with the relevant focal plane structures. Displacements due to thermal growth, etc., in use should be controlled so that the minimum anticipated differential displacements is less than  $\pm 0.1\mu$ .

#### 4.4 COARSE ACQUISITION CAMERA

This camera must be mounted and boresighted to the main telescope line of sight to within  $\pm 1$  min, and should be designed to remain stable to within  $\pm 1$  Sec. These numbers are somewhat arbitrary in nature since they depend to a large extent on the exact mode of operational use of the camera display. However, in the absence of better definition, this preliminary data will serve as a conservative estimate.

#### APPENDIX A

PRIMARY MIRROR SAG TABLES

ASPHERIC SAG TABLE

LST RAUL 09.48.43 03/19/73

A=-1.731380D-02 B= 0.0 C= 0.0

D = 0.0 E = 0.0

CURV. -1.8939411D-04 CURV. SUBTRACTED -1.8873229D-04 SCALING FAC. 1.000

RADIUS (MM) -0.5279995D 04 SUBTRACTED RADIUS (MM) -0.5298510D 04

SURFACE NO. 1

SCALED ASPHERIC COEFFICIENTS

A=-1.731380D-02 B= 0.0

C = 0.0

0 = 0.0

E= 0.0

H (MM)	SAG (MICRONS)	SUB SAG (MICRONS)		
		relative to neavest appeare.		
0.0	0.0	0.0		
5.00	-2.37	-0.008		
10.00	-9.47	-0.033		
15.00	-21.31	-0.074		
20.00	-37.88	-0.132		
25.00	-59.19	-0.206		
30.00	-85.23	-0.297		
35.00	-116.00	-0.404		
40.00	-151.52	-0.527		
45.00	-191.76	-0.667		
50.00	-236.74	-0.822		
55.00	-286.46	-0.993		
60.00	-340.91	-1.180		
65.00	-400.09	-1.383		
70.00	-464.02	-1.601		
75.00	-532.67	-1.834		
80.00	-606.06	-2.083		
85.00	-684.19	-2.346		
90.00	-767.05	-2.624		
95.00	-854.64	-2.917		
100.00	-946.97	-3.224		
105.00	-1044.03	-3.544		
110.00	-1145.83	-3.879		•
115.00	-1252.37	-4.227		
120.00	-1363.63	-4.588		
125.00	-1479.64	-4.962		
130.00	-1600.38	<b>-5.348</b>		
135.00	-1725.85	-5.747	•	
140.00	-1856.06	-6.157		
145.00	-1991.00	-6.579		
150.00	-2130.68	-7.012		
155.00	-2275.09	-7.456		
160.00	-2424.23	-7.911		
165.00	-2578.12	-8.375		

170.00	-2736.73	-8.849
175.00	-2900.08	-9.332
180.00	-3068.17	-9.823
	-3240.99	-10.323
185.00		-10.831
190.00	-3418.54	
195.00	-3600.83	-11.346
200.00	-3787.86	-11.867
205.00	-3979.62	-12.395
210.00	-4176.11	-12-929
215.00	-4377.34	-13.468
220.00	-4583.30	-14.011
225.00	-4794.00	-14.559
230.00	-5009.43	-15.110
235.00	-5229.60	-15.664
240.00	-5454.50	-16.221
245.00	-5684.14	-16.779
250.00	-5918.51	-17.338
255.00	-6157.61	-17.898
260.00	-6401.45	-18.458
265.00	-6650.03	-19.016
270.00	-6903.34	-19.574
275.00	-7161.38	-20.129
280.00	-7424.16	-20.681
285.00	-7691.67	-21.229
290.00	-7963.92	-21.773
295.00	-8240.90	-22.312
300.00	-8522.62	-22.845
305.00	-8809.07	-23.372
310.00	-9100.25	-23.891
315.00	-9396.17	-24.402
320.00	-9696.82	-24.903
325.00	-10002.21	-25.395
330.00	-10312.33	-25.877
335.00	-10627.19	-26.347
340.00	-10946.78	-26.804
345.00	-11271.11	-27.248
350.00	-11600.17	-27.678
355.00	-11933.96	-28.093
360.00	-12272.49	-28.492
365.00	-12615.75	-28.874
370.00	-12963.75	-29.238
375.00	-13316.48	-29.584
380.00	-13673.95	-29.910
385.00	-14036.15	-30.215
390.00	-14403.08	-30.498
	-14774.75	-30.498
395.00	-14114012	-30+137

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415.00
                          -31.684
        -16704.10
420.00
                          -31.786
        -17104.18
425.00
                          -31.859
        -17508.98
430.00
                          -31.899
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435.00
                          -31.908
        -18332.80
440.00
                          -31.883
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        -18751.81
                          -31.823
        -19175.55
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                          -31.727
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                          -31.595
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                          -31.424
        -20475.18
465.00
                          -31.213
        -20917.86
470.00
                          -30.962
475.00
        -21365.27
        -21817.42
                          -30.669
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                          -30.333
        -22274.30
485.00
                          -29.953
        -22735.92
490.00
                          -29.526
         -23202.26
495.00
                          -29.053
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                          -28.532
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525.00
                          -25.153
530.00
         -26599.24
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         -27103.46
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         -27612.41
540.00
                          -22.460
         -28126.10
545.00
                          -21.443
         -28644.51
550.00
                          -20.364
         -29167.67
555.00
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560.00
         -29695.55
                          -18.013
         -30228.17
565.00
                          -16.739
         -30765.52
570.00
                          -15.397
         -31307.61
575.00
                          -13.985
         -31854.43
580.00
                          -12.502
         -32405.98
585.00
                          -10.947
         -32962.26
590.00
                           -9.317
         -33523.28
595.00
                           -7.612
         -34089.03
600.00
                           -5.830
         -34659.52
605.00
         -35234.74
                           -3.968
610.00
                           -2.027
         -35814.69
615.00
         -36399.38
                           -0.003
620.00
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NEAREST SPHERE - RADIUS -5.2985104D 03 MM

CURV.-1.8873229D-04

### APPENDIX B

SECONDARY MIRROR SAG TABLES

#### ASPHERIC SAG TABLE

LST

RAUL

09.48.43 03/19/73

A=-1.254750D 00 B= 0.0

 $C = 0 \cdot 0$ 

0 = 0.0

E = 0.0

CURV. -7.5518869D-04 CURV. SUBTRACTED -7.4978692D-04 SCALING FAC.

1.000

RADIUS (MM) -0.1324172D 04 SUBTRACTED RADIUS (MM) -0.1333712D 04

SURFACE NO. 2

SCALED ASPHERIC COEFFICIENTS

A=-1.254750D 00 B= 0.0

C = 0.0

0 = 0.0

E= 0.0

H(MM)	SAG (MICRONS)	SUB SAG (MICRONS) relative to Neavest sphere.
0.0	0.0	0 • 0
1.00	-0.38	-0.003
2.00	-1.51	-0.011
3.00	-3.40	-0.024
4.00	-6.04	-0.043
5.00	-9.44	-0.067
6.00	-13.59	-0.097
7.00	-18.50	-0.132
8.00	-24.17	-0.172
9.00	-30.58	-0.218
10.00	-37.76	-0.269
11.00	-45.69	-0.325
12.00	-54.37	-0.386
13.00	-63.81	-0.453
14.00	-74.01	-0.525
15.00	-84.96	-0.602
16.00	-96.66	-0.684
17.00	-109.12	-0.771
18.00	-122.33	-0.862
19.00	-136.30	-0.959
20.00	-151.03	-1.061
21.00	-166.51	-1.168
22.00	-182.74	-1.279
23.00	-199.73	-1.395
24.00	-217.47	-1.516
25.00	-235.97	-1.641
26.00	-255.22	-1.771
27.00	-275.23	-1.905
28.00	-295.99	-2.044
29.00	-317.51	-2.186
30.00	-339.78	-2.333
31.00	-362.81	-2.485
32.00	-386.59	-2.640
33.00	-411.12	-2.799

34.00	-436.41	-2.962
35.00	-462.45	-3.128
36.00	-489.25	-3.298
37.00	-516.80	-3.472
	-545.11	-3.649
38.00	-574.16	-3.830
39.00	-603.98	-4.014
40.00	-634 <sub>•</sub> 55	-4.200
41.00	-665.87	-4.390
42.00	-697.94	-4.583
43.00		-4.778
44.00	-730.77 -764.35	-4.976
45.00	<b>-798.69</b>	-5.177
46.00		-5.380
47.00	-833.78	-5.585
48.00	-869.62	-5.792
49.00	-906.21	-6.001
50.00	<b>-943.56</b>	-6.212
51.00	-981.67	-6.424
52.00	-1020.52	-6.638
53.00	-1060.13	<b>-6.854</b>
54.00	-1100.49	-7.070
55.00	-1141.61	<b>-7.288</b>
56.00	-1183.47	<b>-7.506</b>
57.00	-1226.09	<b>-7.725</b>
58.00	-1269.46	-7.945
59.00	-1313.59	-8.165
60.00	-1358-47	-8.386
61.00	-1404.09	-8.606
62.00	-1450 • 48	
63.00	-1497.61	-8.826 -9.046
64.00	-1545.49	<b>-9.266</b>
65.00	-1594.13	<b>-9.484</b>
66.00	-1643.52	-9.702
67.00	-1693.66	-9.919
68.00	-1744.55	-10.134
69.00	-1796.20	-10.134
70.00	-1848.59	
71.00	-1901.74	-10.561 -10.771
72.00	-1955.64	-10.980
73.00	-2010.29	-11.186
74.00	-2065.68	-11.390
75.00	-2121.84	-11.591
76.00	-2178.74	-11.789
77.00	-2236.39	-11.984
78.00	-2294.79	-12.175
79.00	-2353.94	-12.363
80.00	-2413.84	-12.547
81.00	-2474.50	-12.727
82.00	-2535.90	-12.903
83.00	-2598.05	-13.074
84.00	-2660.95	-13.241
85.00	-2724.60	-13.541

86.00	-2789.00	-13.402
	-2854.15	-13.558
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88.00	-2920.05	
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90.00	-3054.09	-13.993
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	-3191.13	-14.252
92.00		-14.371
93.00	-3260.78	
94.00	-3331.17	-14.484
95.00	-3402.30	-14.589
96.00	-3474.19	-14.686
97.00	-3546.82	-14.775
98.00	-3620.21	-14.857
	-3694.34	-14.930
99.00		-14.994
100.00	-3769.21	
101.00	-3844.84	-15.049
102.00	-3921.21	-15.095
103.00	-3998.32	-15.131
104.00	-4076.19	-15.158
105.00	-4154.80	-15.174
		-15.180
106.00	-4234.16	
107.00	-4314.26	-15.175
108.00	-4395.11	-15.159
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112.00	-4725.96	-14.978
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		-14.813
114.00	-4895.86	
115.00	-4981.93	-14.710
116.00	-5068.74	-14.594
117.00	-5156.29	-14.464
118.00	-5244.59	-14.320
119.00	-5333.64	-14.161
120.00	-5423.42	-13.987
		-13.798
121.00	<b>-5513.95</b>	
122.00	-5605.23	-13.593
123.00	-5697.25	-13.372
124.00	-5790.01	-13.134
125.00	-5883.51	-12.880
126.00	-5977.76	-12.609
127.00	-6072.75	-12.321
	-6168.48	-12.014
128.00		
129.00	-6264.95	-11.690
130.00	-6362.17	-11.347
131.00	-6460.12	-10.985
132.00	-6558.82	-10.604
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135.00	-6859.36	-9.340
132.00	-0037630	- 70340

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149.00
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NEAREST SPHERE - RADIUS -1.3337123D 03 MM

CURV .- 7.4978692D-04